

SISTEMAS

$$\Sigma: \begin{cases} a_{11}x_1 + \dots + a_{1n}x_n = b_1 \\ \vdots \\ a_{m1}x_1 + \dots + a_{mn}x_n = b_m \end{cases} \quad a_{ij}, b_j \in K \quad \left| \quad \Sigma: A \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ \vdots \\ b_m \end{pmatrix} \right.$$

$$A = \begin{pmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{pmatrix}$$

Conjunto de soluciones

$$\Sigma(K) = \left\{ (a_{11}, \dots, a_n) \in K^n : a_{11}a_1 + \dots + a_n a_n = b_1, \dots, a_{m1}a_1 + \dots + a_{mn}a_n = b_m \right\}$$

i) ¿ $\Sigma(K) \neq \emptyset$?

ii) $\Sigma(K) \neq \emptyset \Rightarrow \Sigma(K)$?

$b_1 = \dots = b_m = 0 \Rightarrow$ Sistema homogéneo

Lo que hay siempre que comprobar

$$A \cdot \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = 0$$

$$(A|b) \in \text{Mat}_{m \times (n+1)}$$

↳ Matriz ampliada

Teorema

Si Σ es homogéneo, entonces $\Sigma(K)$ es un subespacio vectorial de K^n

de dimensión $n - \text{rg}(A)$



Dem.

$$\Sigma: A \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ \vdots \\ b_m \end{pmatrix} \quad v = (x_1, \dots, x_n)_{B_c} \implies \emptyset(v) = (x'_1, \dots, x'_m)$$

$$\emptyset: K^n \rightarrow K^m \quad \begin{pmatrix} x'_1 \\ \vdots \\ x'_m \end{pmatrix} = A \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \implies \Sigma(K) = \text{Ker}(\emptyset)$$

$$M_{B_c, B_c}(\emptyset) = A$$

$$\implies \Sigma(K) < K^n,$$

$$\dim \Sigma(K) = n - \text{rg}(\emptyset) =$$

$$= n - \text{rg}(A)$$

$$\Sigma: \begin{cases} a_{11}x_1 + \dots + a_{1r}x_r + \dots + a_{1n}x_n = 0 \\ \vdots \\ a_{r1}x_1 + \dots + a_{rr}x_r + \dots + a_{rn}x_n = 0 \\ \vdots \\ a_{m1}x_1 + \dots + a_{mr}x_r + \dots + a_{mn}x_n = 0 \end{cases}$$

Las l.i.

Combinación lineal

Variables independientes

$$\begin{pmatrix} a_{11} & \dots & a_{1r} \\ \vdots & & \vdots \\ a_{r1} & \dots & a_{rr} \end{pmatrix} \begin{pmatrix} x_1 \\ \vdots \\ x_r \end{pmatrix} = \begin{pmatrix} -a_{1r+1}x_{r+1} - \dots - a_{1n}x_n \\ \vdots \\ -a_{rr+1}x_{r+1} - \dots - a_{rn}x_n \end{pmatrix}$$

$$\implies \begin{pmatrix} x_1 \\ \vdots \\ x_r \end{pmatrix} = \begin{pmatrix} a_{11} & \dots & a_{1r} \\ \vdots & & \vdots \\ a_{r1} & \dots & a_{rr} \end{pmatrix}^{-1} \cdot \begin{pmatrix} -a_{1r+1}x_{r+1} - \dots - a_{1n}x_n \\ \vdots \\ -a_{rr+1}x_{r+1} - \dots - a_{rn}x_n \end{pmatrix}$$

Ej.:

$$\Sigma: \begin{cases} x+y-2z+t=0 \\ x-2y+z-2t=0 \\ -2x+y-z+t=0 \end{cases} \sim \Sigma' \begin{cases} x+y-2z+t=0 \\ -3y+z-3t=0 \\ 3y-3z+3t=0 \end{cases} \sim \Sigma'' \begin{cases} x+y-2z+t=0 \\ 3y+3z-3t=0 \\ 0=0 \end{cases}$$

$$A'' = \begin{pmatrix} 1 & 1 & -2 & 1 \\ 0 & -3 & 3 & -3 \\ 0 & 0 & 0 & 0 \end{pmatrix} \quad \Sigma(K) = \Sigma''(K) < K^4, \quad \dim \Sigma(K) = 4 - \text{rg}(A'') = 4 - 2 = 2$$

$$\sim \Sigma''': \begin{cases} x-z=0 \\ -3y+3z-3t=0 \end{cases} \quad A''' = \begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & -3 & 3 & -3 \end{pmatrix} \Rightarrow \Sigma(K) \begin{cases} x=z \\ y=z-t \end{cases} \Rightarrow \Sigma(K) = \{(x,y,z,t) \in K^4, \\ \underline{x=z, y=z-t}\}$$

$\{(0,1,1,0), (0,-1,0,1)\}$ { base de $\Sigma(K)$
 Elegidas

$\text{rg}(A) = \text{rg} \begin{pmatrix} 1 & 1 & -2 & 1 \\ 1 & -2 & 1 & -2 \\ -2 & 1 & 1 & 1 \end{pmatrix} = 2$

$F_3 = -(F_1 + F_2)$ $C_3 = -(C_1 + C_2)$ $C_4 = C_2$ { Vemos que son l.d. }

$\Sigma: \begin{cases} x+y-2z+t=0 \\ x-2y+z-2t=0 \end{cases} \iff P \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2z-t \\ -z+2t \end{pmatrix}$

\Downarrow

$\begin{pmatrix} x \\ y \end{pmatrix} = P^{-1} \begin{pmatrix} 2z-t \\ -z+2t \end{pmatrix}$

la tercera sobra (no aporta nada)

$$P^{-1} = \frac{1}{3} \begin{pmatrix} 2 & 1 \\ 1 & -1 \end{pmatrix}$$

$$\begin{aligned} \implies \begin{pmatrix} x \\ y \end{pmatrix} &= \frac{1}{3} \begin{pmatrix} 2 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 2z-t \\ -z+2t \end{pmatrix} = \\ &= \frac{1}{3} \begin{pmatrix} 2(2z-t) + (-z+2t) \\ (2z-t) - 1(-z+2t) \end{pmatrix} \\ &= \frac{1}{3} \begin{pmatrix} 3z \\ 3z-3t \end{pmatrix} = \underline{\underline{\begin{pmatrix} z \\ z-t \end{pmatrix}}} \end{aligned}$$

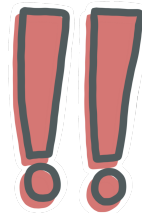
Nunca es un espacio vectorial

$$\Sigma_b : A \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ \vdots \\ b_m \end{pmatrix}$$

$$\Sigma_0 : A \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix}$$

Sistema homogéneo asociado

Teorema de Rouché - Frobenius



i) $\Sigma_b(K) \neq \emptyset \iff \text{rg}(A) = \text{rg}(A|b)$

ii) Si $\Sigma_b(K) \neq \emptyset$, entonces $\Sigma_b(K) = \{ (a_1, \dots, a_n) + (c_1, \dots, c_n) : (c_1, \dots, c_n) \in \Sigma_0(K) \}$
 donde $(a_1, \dots, a_n) \in \Sigma_b(K)$

Dem.

$$\varphi : K^n \rightarrow K^m, M_{B_c, B'_c}(\varphi) = A, v = (x_1, \dots, x_n)_{B_c}, \varphi(v) = (x'_1, \dots, x'_m)_{B'_c}$$

$$\begin{matrix} B_c & B'_c \\ \parallel & \parallel \\ \{e_1, \dots, e_n\} & \{e'_1, \dots, e'_m\} \end{matrix} \implies \begin{pmatrix} x'_1 \\ \vdots \\ x'_m \end{pmatrix} = A \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$$

$$\Sigma_b(K) \neq \emptyset \iff (b_1, \dots, b_m)_{B'_c} \in \text{Im}(\varphi) \iff b_1 e'_1 + \dots + b_m e'_m \in L(\varphi(e_1), \dots, \varphi(e_n))$$

$$\iff L(b_1 e'_1 + \dots + b_m e'_m, \varphi(v_1), \dots, \varphi(v_n)) = \text{Im}(\varphi)$$

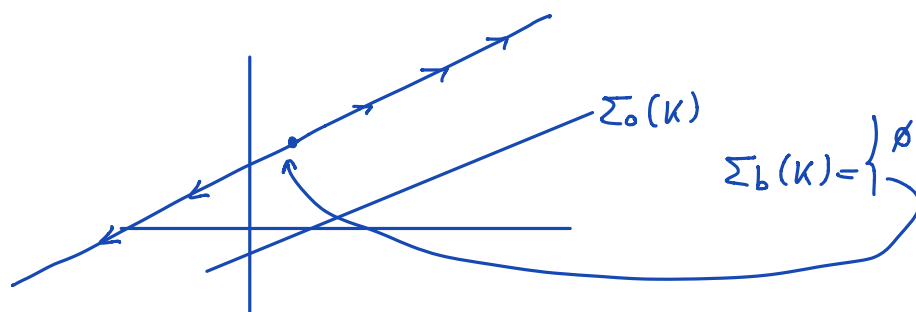
$$\iff \dim L(\underbrace{b_1 e'_1 + \dots + b_m e'_m, \varphi(v_1), \dots, \varphi(v_n)}_{n+1 \text{ vectores columna}}) = \dim \text{Im}(\varphi) = \text{rg} \varphi = \text{rg} A$$

$$\iff \text{rg}(A|b) = \text{rg}(A)$$

ii) Sea $(a_1, \dots, a_n) \in \Sigma_b(K)$

Sea $(a'_1, \dots, a'_n) \in \Sigma_b(K)$ Otra cualquiera

$$\begin{matrix} a'_1 - a_1 & \dots & a'_n - a_n \\ \parallel & & \parallel \\ c_1 & & c_n \end{matrix} \in \Sigma_0(K) \implies (a'_1, \dots, a'_n) = \overset{\in \Sigma_b(K)}{(a_1, \dots, a_n)} + \overset{\in \Sigma_0(K)}{(c_1, \dots, c_n)}$$



Método de Cramer

$$\begin{cases} a_1x + b_1y + c_1z = d_1 \\ a_2x + b_2y + c_2z = d_2 \\ a_3x + b_3y + c_3z = d_3 \end{cases} \quad \text{rg}(A) = 3 \implies |A| \neq 0$$

$$x = \frac{\begin{vmatrix} d_1 & b_1 & c_1 \\ d_2 & b_2 & c_2 \\ d_3 & b_3 & c_3 \end{vmatrix}}{|A|}, \quad y = \frac{\begin{vmatrix} a_1 & d_1 & c_1 \\ a_2 & d_2 & c_2 \\ a_3 & d_3 & c_3 \end{vmatrix}}{|A|}, \quad z = \frac{\begin{vmatrix} a_1 & b_1 & d_1 \\ a_2 & b_2 & d_2 \\ a_3 & b_3 & d_3 \end{vmatrix}}{|A|}$$

Dem.

Sean x, y, z las soluciones únicas. Los interpretamos como elementos de K

$$\begin{vmatrix} d_1 & b_1 & c_1 \\ d_2 & b_2 & c_2 \\ d_3 & b_3 & c_3 \end{vmatrix} = \begin{vmatrix} a_1x + b_1y + c_1z & b_1 & c_1 \\ a_2x + b_2y + c_2z & b_2 & c_2 \\ a_3x + b_3y + c_3z & b_3 & c_3 \end{vmatrix} = \begin{vmatrix} a_1x & b_1 & c_1 \\ a_2x & b_2 & c_2 \\ a_3x & b_3 & c_3 \end{vmatrix} + \begin{vmatrix} b_1y & b_1 & c_1 \\ b_2y & b_2 & c_2 \\ b_3y & b_3 & c_3 \end{vmatrix} + \begin{vmatrix} c_1z & b_1 & c_1 \\ c_2z & b_2 & c_2 \\ c_3z & b_3 & c_3 \end{vmatrix} =$$

$$= x \cdot |A| + y \cdot 0 + z \cdot 0 = x \cdot |A|$$

Análogo para y, z . (Demostración válida para cualquier $n \times n$)

rango = tamaño máximo de un menor

$$\text{rg}(A) = r, \quad A \in \text{Mat}_{m \times n}(K)$$

$$A = \begin{pmatrix} a_{11} & \dots & a_{1r} & \dots & a_{1n} \\ \vdots & & \vdots & & \vdots \\ a_{r1} & \dots & a_{rr} & \dots & a_{rn} \\ \vdots & & \vdots & & \vdots \\ a_{m1} & \dots & a_{mr} & \dots & a_{mn} \end{pmatrix} \left\{ \begin{array}{l} \text{Vectores} \\ \text{p.i.} \end{array} \right. \implies \text{rg} \left(\begin{array}{ccc} a_{11} & \dots & a_{1r} & \dots & a_{1n} \\ \vdots & & \vdots & & \vdots \\ a_{r1} & \dots & a_{rr} & \dots & a_{rn} \end{array} \right) = r$$

p.i. (ya que hay r columnas indep)

$$\implies \text{rg} \begin{pmatrix} a_{11} & \dots & a_{1r} \\ \vdots & & \vdots \\ a_{r1} & \dots & a_{rr} \end{pmatrix} = r$$

Supongamos $t > r \implies$ No habrá submatrices que den mayor rango

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